

# DBS60E-THFK00S44

DBS60

**INCREMENTAL ENCODERS** 



Illustration may differ

#### Ordering information

Туре	Part no.
DBS60E-THFK00S44	1080992

Other models and accessories → www.sick.com/DBS60



#### Detailed technical data

#### **Features**

Special device	✓	
Specialty	Cable, 8-wire, universal 1.5 m with customized wire color	
Standard reference device	DBS60E-THFK01024,1077725	

#### Performance

Pulses per revolution	1,024
Measuring step	≤ 90°, electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 5 %

#### Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL 1)
Number of signal channels	6-channel
Initialization time	< 5 ms <sup>2)</sup>
Output frequency	+ 300 kHz <sup>3)</sup>
Load current	≤ 30 mA, per channel
Power consumption	≤ 0.5 W (without load)

<sup>1)</sup> Output level depends on the supply voltage.

#### Electrical data

Connection type	Cable, 8-wire, universal, 1.5 m <sup>1)</sup>
Supply voltage	4.5 30 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

 $<sup>^{\</sup>rm 2)}\,{\rm Valid}$  signals can be read once this time has elapsed.

 $<sup>^{3)}</sup>$  Up to 450 kHz on request.

 $<sup>^{2)}\,\</sup>mbox{Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.$ 

<sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reverse polarity protection	✓
Short-circuit protection of the outputs	<b>✓</b> <sup>2)</sup>
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) 3)

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

#### Mechanical data

Mechanical design	Through hollow shaft, Front clamp	
Shaft diameter	15 mm	
Flange type / stator coupling	2-sided stator coupling, slot, screw hole circle 63–83 mm	
Weight	+ 0.25 kg <sup>1)</sup>	
Shaft material	Stainless steel	
Flange material	Aluminum	
Housing material	Aluminum	
Material, cable	PVC	
Start up torque	+ 0.5 Ncm (+20 °C)	
Operating torque	0.4 Ncm (+20 °C)	
Permissible movement static	$\pm$ 0.3 mm (radial) $\pm$ 0.5 mm (axial) <sup>2)</sup>	
Permissible movement dynamic	$\pm$ 0.1 mm (radial) $\pm$ 0.2 mm (axial) $^{2)}$	
Operating speed	6,000 min <sup>-1 3)</sup>	
Maximum operating speed	9,000 min <sup>-1 4)</sup>	
Moment of inertia of the rotor	50 gcm <sup>2</sup>	
Bearing lifetime	3.6 x 10 <sup>9</sup> revolutions	
Angular acceleration	≤ 500,000 rad/s²	

 $<sup>^{1)}</sup>$  Based on encoder with male connector or cable with male connector.

#### Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3	
Enclosure rating	IP65, housing side (IEC 60529) IP65, shaft side (IEC 60529)	
Permissible relative humidity	90 % (Condensation not permitted)	
Operating temperature range	-30 °C +100 °C, at maximum 3,000 pulses per revolution <sup>1)</sup>	
Storage temperature range	-40 °C +100 °C, without package	
Resistance to shocks	250 g, 3 ms (EN 60068-2-27)	
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)	

<sup>&</sup>lt;sup>1)</sup> These values relate to all mechanical versions including recommended accessories unless otherwise noted.

 $<sup>^{2)}\,\</sup>mathrm{Short\text{-}circuit}$  opposite to another channel, US or GND permissable for maximum 30 s.

<sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $<sup>^{2)}\,\</sup>mathrm{Not}$  apllicable for stator coupling type C and K.

 $<sup>^{3)}</sup>$  Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

<sup>&</sup>lt;sup>4)</sup> Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

# **DBS60E-THFK00S44 | DBS60**

INCREMENTAL ENCODERS

#### Classifications

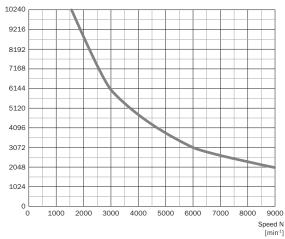
ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

## PIN assignment

Core colors of encoders with cable outlet	TTL/HTL signal	Explanation
Yellow	- A	Signal cable
Green	Α	Signal cable
Pink	-В	Signal cable
Grey	В	Signal cable
Red	-Z	Signal cable
Blue	Z	Signal cable
White	GND	Ground connection of the encoder
Brown	+U <sub>s</sub>	Supply voltage (volt-free to housing)
Shield	Shield	Shield connected to housing on side of encoder. Connected to ground on side of control.

### Diagrams

Pulses per revolution



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