

AFM60B-TGRK000S05

AFS/AFM60 SSI

ABSOLUTE ENCODERS



Illustration may differ

Ordering information

Туре	Part no.
AFM60B-TGRK000S05	1068855

Other models and accessories → www.sick.com/AFS_AFM60_SSI



Detailed technical data

Features

Special device	√
Specialty	Customized stator coupling 2047430 Cable, 12-wire, radial, 0.857 m, with M23 12-pin male connector Preprogramming of electrical interface with HTL setting and preprogramming of SSI with 08192 increments
Standard reference device	AFM60B-TGRK032768, 1080475

Performance

Number of steps per revolution (max. resolution)	32,768 (15 bit)
Number of revolutions	4,096 (12 bit)
$\label{eq:max_problem} \begin{tabular}{ll} \textbf{Max. resolution (number of steps per revolution x number of revolutions)} \end{tabular}$	15 bit x 12 bit (32,768 x 4,096)
Error limits G	0.05° ¹⁾
Repeatability standard deviation $\boldsymbol{\sigma_r}$	0.002° ²⁾

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

Interfaces

Communication interface	SSI
Communication Interface detail	SSI + incremental
Initialization time	50 ms ¹⁾
Position forming time	< 1 µs
Code type	Gray
Code sequence parameter adjustable	CW/CCW (V/R) parameter adjustable
Clock frequency	≤ 2 MHz ²⁾
Set (electronic adjustment)	H-active (L = $0 - 3 \text{ V}$, H = $4,0 - U_s \text{ V}$)
CW/CCW (counting sequence when turning)	L-active (L = 0 - 1,5 V, H = 2,0 - Us V)
Pulses per revolution	1/4 of number of SSI steps per revolution
Output frequency	≤ 600 kHz

 $^{^{1)}}$ Valid positional data can be read once this time has elapsed.

 $^{^{2)}}$ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

²⁾ Minimum, LOW level (Clock +): 250 ns.

 $^{^{1)}}$ Valid positional data can be read once this time has elapsed.

Electrical data

Connection type	Cable, 12-wire, radial, 1.5 m
Supply voltage	4.5 32 V DC
Power consumption	≤ 0.7 W (without load)
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	250 years (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Through hollow shaft
Shaft diameter	14 mm
Weight	$0.2~{ m kg}^{~1)}$
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	< 0.8 Ncm (+20 °C)
Operating torque	< 0.6 Ncm (+20 °C)
Permissible movement static	± 0.5 mm (axial) ± 0.3 mm (radial)
Permissible movement dynamic	± 0.2 mm (axial) ± 0.1 mm (radial)
Operating speed	≤ 9,000 min ^{-1 2)}
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.0 x 10^9 revolutions
Angular acceleration	≤ 500,000 rad/s²

¹⁾ Based on devices with male connector.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3 $^{1)}$
Enclosure rating	IP65, shaft side (IEC 60529) IP67, housing side (IEC 60529) ²⁾
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +100 °C ³⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)

¹⁾ EMC according to the standards quoted is achieved if shielded cables are used.

 $^{^{2)}}$ Minimum, LOW level (Clock +): 250 ns.

 $^{^{2)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

 $^{^{\}rm 2)}$ For devices with male connector: with mounted mating connector.

³⁾ Stationary position of the cable.

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Resistance to vibration

30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

Classifications

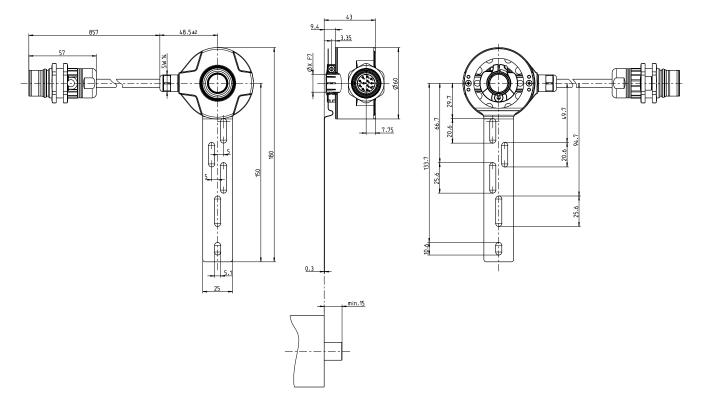
ECLASS 5.0	27270502
ECLASS 5.1.4	27270502
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270502
ECLASS 8.0	27270502
ECLASS 8.1	27270502
ECLASS 9.0	27270502
ECLASS 10.0	27270502
ECLASS 11.0	27270502
ECLASS 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

 $^{^{1)}\,\}mathrm{EMC}$ according to the standards quoted is achieved if shielded cables are used.

²⁾ For devices with male connector: with mounted mating connector.

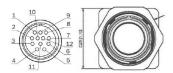
 $^{^{}m 3)}$ Stationary position of the cable.

Dimensional drawing (Dimensions in mm (inch))

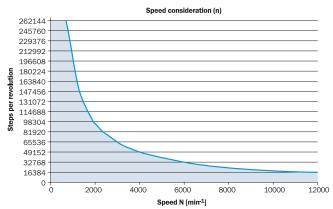


PIN assignment

Pin	Signal	Explanation
1	+U _s	Supply voltage
2	GND	Ground connection
3	Clock+	Interface signal
4	Data+	Interface signal
5	SET	Electronic adjustment
6	Data-	Interface signal
7	Clock-	Interface signal
8	B	Signal line
9	CW/CCW	Counting sequence when turning
10	Ā	Signal line
11	A	Signal line
12	В	Signal line
	Screen	Screen on the encoder side connected to the housing. On the control side connected to earth,



Diagrams



The maximum speed is also dependent on the shaft type.

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